# LINEAR TRANSDUCERS

# HIGH RELIABILITY EVEN IN THE HEAVY ENVIRONMENTS

Easy installation made easier for the presence of a groove in the housing potentiometer represent an ideal solution for the most used machine of material manufacture, for example injection press for plastic and gum.

for high accuracy, high cycle-life and easy installation. Standard strokes are from 10 (4/10") mm to 1250 mm (4 ft).

ELTRA's linear transducers provide accurate sensing in a wide range of configurations. Rod style for fitting within hydraulic pistons or profile housing for a convenient mounting are available.

ELTRA's linear transducers are engineered ELTRA's linear sensors feature absolute positioning, greater reliability, easy control, noise reduction, robustness, increased productivity, reduced shock and stress on mechanical parts, high precision for high performances, costeffective solutions.



## ER A / B / C / D / E / F **INCREMENTAL LINEAR ENCODER**



Incremental linear system based on optical or magnetic principle. Easy mounting due to to joint heads.

- 0,01 mm max resolution (after quad eval)
- Available with or without zero mark on left, right or central position
- Up to 1 m/s travel speed
- Working stroke up to 500 mm
- Cable output, connector available on cable end
- Mounting by joint heads

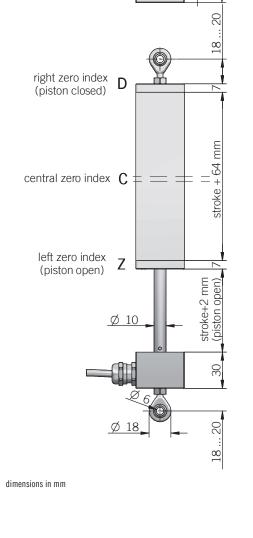
**ORDERING CODE** 











A/B/C/D/E/F



### ER 100 S 8/24 Р 6 P.XXX A SERIES incremental linear encoder ER RESOLUTION 0,2 mm <mark>A</mark> 0,1 mm B 0,04 mm C 1 mm D 0,5 mm <mark>E</mark> 0,2 mm F WORKING STROKE working stroke (mm) from 100 to 500 ZERO PULSE without zero pulse S (mod. A) central zero index C (mod. A) right zero index (closed position) D (mod. A) left zero index (open position) Z POWER SUPPLY 5 V DC 5 8 ... 24 V DC 8/24 ELECTRICAL INTERFACE (mod. A) NPN open collector C push-pull F line driver L **BALL JOINTS FIXING HOLE DIAMETER** mm <mark>6</mark> OUTPUT TYPE radial cable (standard length 1,5 m) P preferred cable lengths 2 / 3 / 5 / 10 m, to be added after output type VARIANT custom version XXX

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## LINEAR TRANSDUCERS | ER A / B / C / D / E / F

ELECTRICAL SPECIFICATIONS				
Technology	optical mod. A magnetic mod. B / C / D / E / F			
Resolution	$\begin{array}{l} A \ / \ F = 0,2 \ mm \ (0,05 \ mm \ after \ quad \ eval) \\ B = 0,1 \ mm \ (0,025 \ mm \ after \ quad \ eval) \\ C = 0,04 \ mm \ (0,01 \ mm \ after \ quad \ eval) \\ D = 1 \ mm \ (0,25 \ mm \ after \ quad \ eval) \\ E = 0,5 \ mm \ (0,125 \ mm \ after \ quad \ eval) \end{array}$			
Linearity error	$\pm$ 1/4 pulse			
Power supply $^{1}$	5 = 4,5 5,5 V DC 8/24 = 7,6 25,2 V DC mod. A 8/24 = 4,5 30 V DC (reverse polarity protection) mod. B / C / D / E / F			
Current consumption without load	< 100 mA max			
Max load current	50 mA / channel (NPN open) 20 mA / channel (push pull / line driver)			
Electrical interface <sup>2</sup>	NPN open collector (pull-up max +30 V DC) push-pull line driver HTL (AEIC-7272)			
Max output frequency	100 kHz			
Counting direction	A leads B (piston opening) mod. A B leads A (piston opening) mod. B / C / D / E / F			
Electromagnetic compatibility	according to 2014/30/EU directive			
RoHS	according to 2015/863/EU directive			
UL / CSA	certificate n. E212495			
MECHANICAL SPECIFICATIONS				
Working stroke	100 - 150 - 200 - 250 - 300 - 350 - 400 - 500 mm			
Enclosure rating	IP 64 (IEC 60529)			
Travel speed	1 m/s max			
Shock	50 G, 11 ms (IEC 60068-2-27)			
Vibration	10 G, 10 2000 Hz (IEC 60068-2-6)			
Rod material	1.4305 / AISI 303 stainless steel			
Housing material	painted aluminum			
Fixing	n.2 ball joints with ø 6 mm hole			
Operating temperature <sup>3, 4</sup>	-10° +60°C (+14° +140°F)			
Storage temperature <sup>4</sup>	-25° +70°C (-13° +158°F)			
Weight				
<sup>1</sup> as measured at the transducer without	cable influences			

<sup>2</sup> for further details refer to OUTPUT LEVELS on TECHNICAL BASICS section

<sup>3</sup> measured on transducer housing <sup>4</sup> condensation not allowed

## CONNECTIONS

GUNNEGTIONS		
Function	Cable C / P	Cable L
+V DC	red	red
0 V	black	black
A+	green	green
A-	/	brown or grey
B+	yellow	yellow
В-	/	orange
Z+	blue	blue
Z-	/	white
÷	shield	shield





# ETMA 1 / 2 / 4 / 5 / 6 MAGNETIC INCREMENTAL LINEAR SENSOR

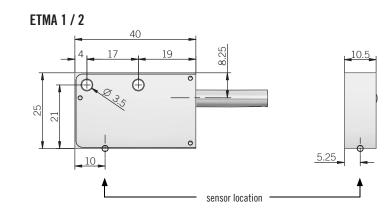


Incremental linear system based on magnetic principle without wear thanks to no-contact technology. Thanks to high IP rating ETMA is suitable for harsh environment applications such as marble and glass working machines, washing systems machines.

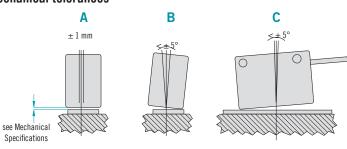
- Resolution up to 0,01 mm
- Power supply up to +30 V DC with several electrical interfaces available
- Up to 4 m/s travel speed
- IP 67 as protection grade

Cable output, connector available on cable end





**Mechanical tolerances** 



dimensions in mm

ELECTRICAL SPECIFICA	TIONS	MECHANICAL SPECIFIC	ATIONS					
	1 = 0.1  mm (0.025  mm after quad eval)	Enclosure rating						
Resolution	2 = 0.04  mm (0.01  mm after quad eval) 4 = 0.2  mm (0.05  mm after quad eval)	Shock	Shock 50 G, 11 ms (IEC 60068-2-27)					
Kesolution	5 = 0.5  mm (0.125  mm after quad eval)	Vibration	20 G, 10 2000 Hz (IEC 60068-2-6)					
	6 = 1  mm (0.25  mm after quad eval)	Housing material	anodized aluminium					
Zero pulse	ETMA 1 / 4 / 5 = every 5 mm ETMA 2 / 6 = every 2 mm	Fixing	n. 2 holes ø 3,5 mm					
	5 = 4,5 5,5 V DC	Operating temperature <sup>3,4</sup>	-20° +85°C (-4° +1	85°F)				
Power supply <sup>1</sup>	$5/28 = 4,5 \dots 30$ V DC (reverse polarity protection)	Storage temperature <sup>4</sup>	-25° +70°C (-13° +158°F)					
Current consumption without load	30 mA max	-	ETMA 1 / 4 / 5 < 1,5mm with magnetic tape protection					
Max load current	20 mA / channel	Working distance from magnetic tape						
Electrical interface <sup>2</sup>	push-pull / line driver HTL (AEIC-7272) line driver RS-422 (AELT-5000 or equivalent)		< 0,5mm with magnetic tape protection < 1mm without cover					
Linearity error	± 1/4 pulse	Weight	150 g (5,29 oz)					
Travel speed	4 m/s							
Electromagnetic compatibility	according to 2014/30/EU directive	CONNECTIONS						
RoHS	according to 2015/863/EU directive	- Function	Cable	Cable				
UL / CSA	certificate n. E212495	- runction	P	L / RS				
<sup>1</sup> as measured at the transducer without		+V DC	red	red				
<ul> <li><sup>2</sup> for further details refer to OUTPUT LEVELS</li> <li><sup>3</sup> measured on transducer housing</li> </ul>	OU LECHINICAL RASICS SECTION	0 V	black	black				
inductive of the second s								

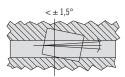
<sup>4</sup> condensation allowed

ORDERING CODE		ETMA	1	Z	5	L	S	PR3	. XXX
		SERIES							
п	nagnetic incremental linear sens		OLUTION						
		0	,1 mm 1						
		0	04 mm 2 ,2 mm 4						
		0	,5 mm 5 1 mm 6						
				RO PULSE					
		W		ro pulse S ro pulse Z					
				POWER	R SUPPLY				
		(with	L electrica	al interface) 5 28 V	5 V DC 5 / DC 5/28				
					TRICAL IN	TERFACE			
						sh-pull P e driver L			
		р	ower supp	oly 5/28 V -	- output R	S-422 <mark>RS</mark>			
					E	ENCLOSUR	E RATING IP 67 S		
							OUTF	UT TYPE	
		prefe	rred cable	lengths 6 / 1	10 / 20 m. t		able length after output		
		,		3 , .	,.				VARIANT
							(	custom ver	'SION XXX

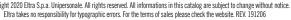




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Function	Cable P	Cable L / RS
+V DC	red	red
0 V	black	black
A+	green	green
A-	/	brown or grey
B+	yellow	yellow
B-	/	orange
Z+	blue	blue
Z-	/	white
÷	shield	shield







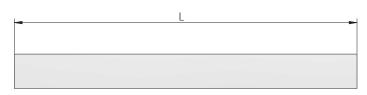
## EBMA **INCREMENTAL MAGNETIC TAPE**



## EBM 10 . XXX SERIES magnetic tape EBM TAPE TYPE 10 mm width magnetic tape A **PITCH** 5mm pitch for ETMA 1 / 4 / 5 1 2mm pitch for ETMA 2 / 6 2 separate the code with a dash TAPE LENGTH from 0,5 m to 50 m 10 VARIANT custom version XXX

## EBMA

**ORDERING CODE** 

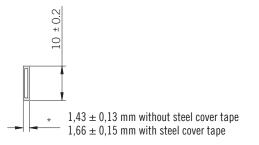


dimensions in mm

for fixing clips please refer to Accessories

## **GENERAL SPECIFICATIONS**

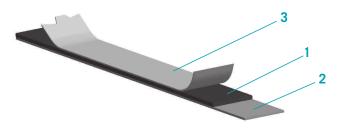
Operating temperature	-20° +100°C (-4° +212°F)
Accuracy	± 40 μm/m
Linear expansion coefficient	17 x 10 <sup>-6</sup> m/К
Bending radius	<ul> <li>&gt; 65 mm without steel cover tape</li> <li>&gt; 100 mm with steel cover tape</li> </ul>
	·



## CONSTRUCTION

As shown in the figure below, Eltra magnetic tape is composed by three layers:

- 1 a flexible magnetic tape made of elastomer filled with ferrite
- correct mechanical rigidity to the magnetic tape. The stainless steel tape is supplied with an acrylic double side adhesive (thickness 0,13 mm) not shown in the figure
- to transport and application needs. It must be sticked on the magnetic tape by the user The steel tape is supplied with an acrylic double side adhesive (thickness 0,13 mm) not shown in the figure



To prevent damage from possible internal stresses in the magnetic tape rolled up with magnetic layer facing outwards, with a minimum internal diameter of 200 mm; keep of least 5 mm between the layers. If supplied in single strip keep at least 10 mm between the strips.

## TIPS TO STICK THE MAGNETIC TAPE ON

## Fixing pressure

The magnetic tape is adhesive. Therefore it is important an optimum contact between the surfaces for right use. A good pressure must be uniformly applied to guarantee a perfect result.

## Applying temperature

In order to guarantee optimal sticking it is recommended a surface temperature between +20°C and +37°C (+68°F to +98,6°F). Maximum adhesion is obtained after 72 hours at temperature of +21°C (+69,8°F). Please do not apply magnetic tape when the surface temperature is lower than +10°C (+50°F).

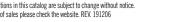
## Application materials

Magnetic tape must be placed on dry, smooth and clean surfaces. The surfaces must be cleaned with aqueous solution (like water and alcohol 50% or heptane). Metallic surfaces like brass, copper etc. must be protected to prevent possible oxidation.

Null effect	Medium effect	Strong effect
motor oil	JP-4 fuel	aromatic hydrocarbons (benzene, toluene, xylene, trichloroethylene, freon 10)
transmission oil	gasoline	ketones (acetone)
ATF (automatic transmission fluid)	heptane	mineral acids (hydrochloric, sulphuric, nitric, phosphoric, boric)
hydraulic oil	alcohols	
kerosene		
antifreeze		
detergents, disinfectants (Clorox®)		
turpentine		
water		
salt spray		



2 - a stainless steel tape used to create a shield against any external magnetic fluxes and other external agents. Furthermore it's glued to the upper layer in order to give the 3 - a steel tape, magnetically transparent and with the function to protect mechanically the magnetic layer; it is the most rigid part and therefore is supplied separately due







## TMAA MAGNETIC ABSOLUTE LINEAR SENSOR

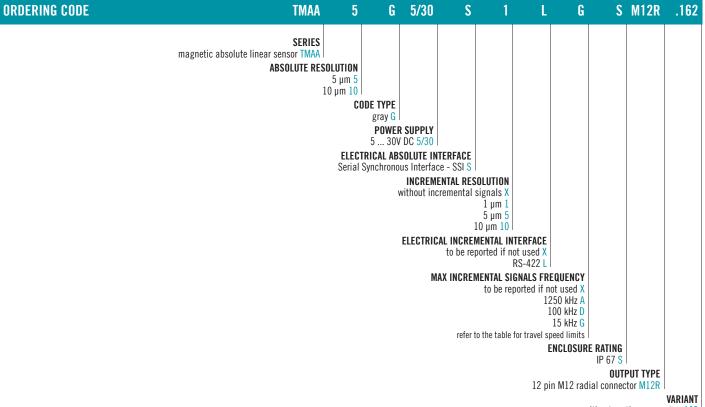
## MAIN FEATURES

Absolute linear system based on magnetic principle without wear thanks to no-contact technology. Thanks to high IP rating TMAA is suitable for harsh environment applications such as marble and glass working machines or washing systems machines.

- $\cdot~$  5  $\mu m$  max absolute resolution / 1  $\mu m$  incremental resolution
- Power supply up to +30 V DC with SSI electrical interface
- Up to 5 m/s travel speed
- · IP 67 as protection grade
- · M12 radial connector
- To be used with BMAA magnetic tape



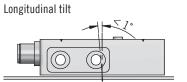




without mating connector .162

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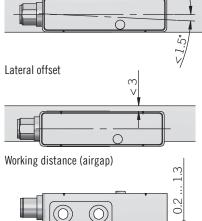
Mounting tolerances





Lateral tilt

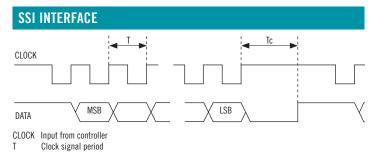




dimensions in mm

for connector please refer to Accessories

INCREMENTAL FREQUENCY - TRAVEL SPEED					
Resolution (µm)	Travel speed (m/s)				
1	4	0,32	0,05		
5	20	0,25			
10	25 3,20 0,50				
Max frequency (Khz)	1250	100	15,63		



Tc Pause time

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ELECTRICAL SPECIFICA	TIONS			
Absolute resolution	5 - 10 µm			
Incremental resolution	1 - 5 μm			
Stroke	$\leq$ 10240 mm			
Power supply <sup>1</sup>	4,5 30 V DC (reverse polarity protection)			
Power draw without load	< 1,5 W			
Electrical interface for absolute signals <sup>2</sup>	RS-422			
Electrical interface for incremental signals <sup>2</sup>	RS-422			
Clock frequency	50 750 kHz			
Pause time (Tc)	> 25 µs			
SSI frame	(MSB LSB) 27 bit data lenght 24 bit data + 3 bit status			
Code type	gray			
Accuracy (sensor+tape)	± (0,02 + 0,03 x lenght) mm lenght in meter			
Repeatability	$\pm$ 5 µm, $\pm$ 1 increment			
Max travel speed	$d \leq 5$ m/s for absolute output refer to the table for incremental output			
Electromagnetic compatibility	according to 2014/30/EU directive			
RoHS	according to 2015/863/EU directive			
MECHANICAL SPECIFIC				
Enclosure rating	IP 67 (IEC 60529)			
Shock	50 G, 11 ms (IEC 60068-2-27)			
Vibration	20 G, 10 2000 Hz (IEC 60068-2-6)			
Housing material	zinc die-cast			
Operating temperature <sup>3, 4</sup>	-30° +85°C (-22° +185°F)			
Storage temperature <sup>4</sup>	-40° +85°C (-40° +185°F)			
Working distance from magnetic tape without steel cover tape	0,2 1,3 mm			
Weight	80 g (2 82 oz)			

**Weight** 80 g (2,82 oz)

<sup>1</sup> as measured at the transducer without cable influences

<sup>2</sup> for further details refer to OUTPUT LEVELS on TECHNICAL BASICS section

<sup>3</sup> measured on transducer housing

<sup>4</sup> condensation allowed

## CONNECTIONS

oonneo maa					
Function	M12 connector 12 pin				
+ V DC	5				
0 V	12				
A+	7				
A-	6				
B+	9				
В-	8				
DATA +	2				
DATA -	3				
CLOCK +	11				
CLOCK -	4				
PROG	10				
	A12 connector (12 nin)				



M12 connector (12 pin) M12 A coded solder side view FV







## MAIN FEATURES

- Magnetic tape to be used with TMAA
- Easy mounting due to premounted double side adhesive
- High pole accuracy
- Available in reels up to 75 m



ORDERING CODE				BN	ЛА	A	50	-	1	. XXX
				SER magnetic tape B 20 mm width ma	MA   TAPE T gnetic ta ACC	pe A CURACY ± 50	<b>f CLASS</b> ) μm 50 code with a	<b>TAPE</b> 0,2 .	: <b>LENGTH</b> 75 m 1	
BMAA			-					in interval		VARIANT sion XXX
			-	* 1,4 mn 1,58 m	ו withou m with s	t steel steel c	cover ta	pe e		
5 STROKE 70	5	Minimum tape lenght (mi	m) = 70 + 10	+ STROKE						

## dimensions in mm

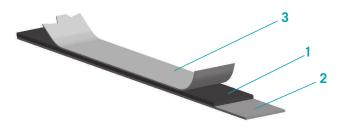
for fixing clips please refer to Accessories

GENERAL SPECIFICATIO	GENERAL SPECIFICATIONS		
Operating temperature	-20° +70°C (-4° +158°F)		
Storage temperature	-40° +70°C (-40° +158°F)		
Relative humidity	100%		
Accuracy	± 50 μm		
Linear expansion coefficient	$(11 \pm 1) \times 10^{-6} \text{ m/K}$		
Bending radius	> 350 mm		



As shown in the figure below, Eltra magnetic tape is composed by three layers:

- 1 a flexible magnetic tape made of elastomer filled with ferrite
- correct mechanical rigidity to the magnetic tape. The stainless steel tape is supplied with an acrylic double side adhesive (thickness 0,1 mm) not shown in the figure
- to transport and application needs. It must be sticked on the magnetic tape by the user The steel tape is supplied with an acrylic double side adhesive (thickness 0,1 mm) not shown in the figure



To prevent damage from possible internal stresses in the magnetic tape rolled up with magnetic layer facing outwards, with a minimum internal diameter of 200 mm; keep of least 5 mm between the layers. If supplied in single strip keep at least 10 mm between the strips.

## TIPS TO STICK THE MAGNETIC TAPE ON

## Fixing pressure

The magnetic tape is adhesive. Therefore it is important an optimum contact between surfaces for right use. A good pressure must be uniformly applied to guarantee a perfect result.

## Applying temperature

In order to guarantee optimal sticking it is recommended a surface temperature between +20°C and +37°C (+68°F to +98,6°F). Maximum adhesion is obtained after 72 hours at temperature of +21°C (+69,8°F). Please do not apply magnetic tape when surface temperature is lower than +10°C (+50°F).

## **Application materials**

Magnetic tape must be placed on dry, smooth and clean surfaces. Surfaces must be cleaned with aqueous solution (like water and alcohol 50% or heptane). Metallic surfaces like brass, copper etc. must be protected to prevent possible oxidation.

Null effect	Medium effect	Strong effect
motor oil	JP-4 fuel	aromatic hydrocarbons (benzene, toluene, xylene, trichloroethylene, freon 10)
transmission oil	gasoline	ketones (acetone)
ATF (automatic transmission fluid)	heptane	mineral acids (hydrochloric, sulphuric, nitric, phosphoric, boric)
hydraulic oil	alcohols	
kerosene		
antifreeze		
detergents, disinfectants (Clorox®)		
turpentine		
water		
salt spray		



2 - a stainless steel tape used to create a shield against any external magnetic fluxes and other external agents. Furthermore it's glued to the upper layer in order to give the 3 - a steel tape, magnetically transparent and with the function to protect mechanically the magnetic layer; it is the most rigid part and therefore is supplied separately due





FE **ROPE ENCODER FOR LINEAR MEASURES** 

MAIN FEATURES

Rope encoder series with Dyneema rope available for lengths up to 4 m. The applied encoder could be incremental or absolute. Perfectly suitable also for harsh enviroments, thanks to its high mechanical strength. It can be used in wide range of applications such as: vertical storehouses, presses, extruders, etc.





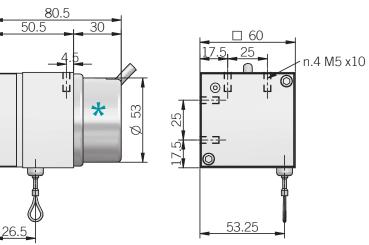
FE 1500

For encoder specifications, refer to single product datasheet :

- FEH 30 M see EH 30 M - EH 30 MH encoder - FEL 53 B see EL - ER 53 encoder

- FEAMR 53 B see EAMR 58 - 63 solid shaft encoder - FEAML 53 B see EAML 58 - 63 solid shaft encoder

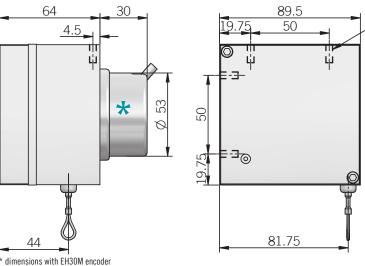
A - EH30



\* dimensions with EH30M encoder

FE 4000 64

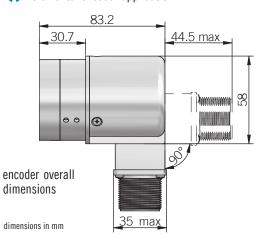
FE 1500



FEL 53 B

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**\*** incremental encoder application



SERIE rope encoder for linear measures F		
WORK	NG STROKE	
	l,5 m 1500 4 m 4000	
	TYPE OF ROPE EN eyelet	
	ENCODE	R FLANGE MODEL
The encoder applied to the FE model must be ordered separately. The F letter must be placed before the ordering code.		EH30 EL/ER53 EAM53
Example: 1) encoder model EH 30 M ordering code: FEH30M300S5/28P6X6PR 2) encoder model EL 53 B ordering code: FEL53B1100S5/28P6X3MR		

Complete ordering code example: FE1500A-EH30 FEH30M1024S5/28P6X6PR

**ORDERING CODE** 

MECHANICAL SPECIFICATIONS			
Model	FE 1500 FE 4000		
Linearity error	± 0,75 mm ± 2 mm		
Drum circumference	120 mm 220 mm		
Max speed	0,85 m/s		
Pull-out force required	$\geq$ 9 N		
Enclosure rating	depends on encoder IP		
Shock	50 G, 11 ms (IEC 60068-2-27)		
Vibration	10 G, 10 2000 Hz (IEC 60068-2-6)		
Housing material	painted aluminum		
Rope material	I Dyneema®		
Operating temperature	-10° +60°C (+14° +140°F)		
Storage temperature	-25° +70°C (-13° +158°F)		
Weight	nt 500 g (17,64 oz) mod. 1500 1100 g (38,80 oz) mod. 4000		

3) encoder model EAMR 53 B ordering code: FEAMR53B12/13G8/30SX6XM12R 4) encoder model EAML 53 B ordering code: FEAML53B16B12/30V010X6M12R

Mechanical resolution [mm] = Drum circumference [mm] / Encoder pulses [ppr o singleturn resolution]

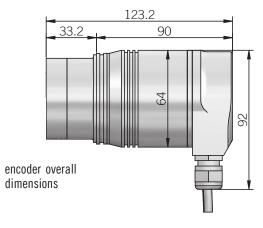


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## LINEAR TRANSDUCERS | FE

n.4 M5 x10









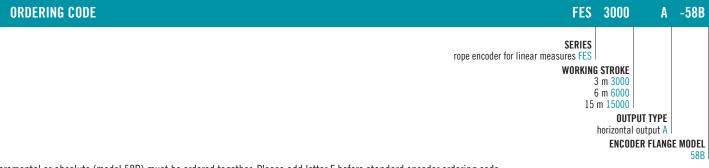
## FES **ROPE ENCODER FOR LINEAR MEASURES**

## MAIN FEATURES

Rope encoder series with steel rope available for lengths up to 15 m. The attached encoder can be incremental or absolute. Perfectly suitable also for harsh environments, thanks to its excellent mechanical strength. It can be used in wide range of applications such as: vertical warehouses, presses, extruders, etc.







Incremental or absolute (model 58B) must be ordered together. Please add letter F before standard encoder ordering code.

## Example:

1) with incremental encoder ordering code will be : FER58B .

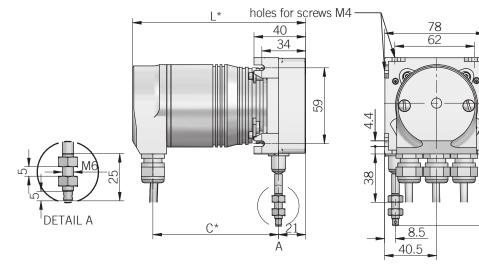
2) with absolute multiturn encoder ordering code will be : FEAMR58BR .

3) with absolute Profinet multiturn encoder ordering code will be : FAAM58B ...

# Complete ordering code example: **FES3000A-58B**

FER58B1024Z5/28L6X3PR

## **FES 3000**



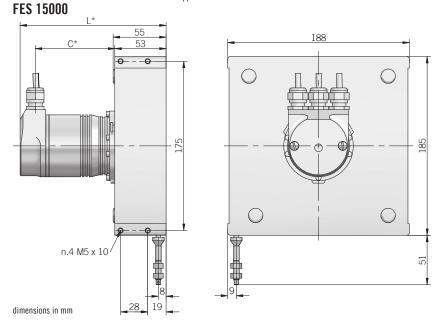




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**FES 6000** 18  $C^*$ 35 33 ŝ Ë 15 04 4.5 ₿ DETAIL 8.5 А



MECHANI	CAL SPECIFICATIONS	
	GAL SPECIFICATIONS	

Model	FES 3000	FES 6000	FES 15000
Max length measurement	3 m	6 m	15 m
Drum circumference	200 mm	200 mm	500 mm
Wire diameter	0,87 mm	0,54 mm	0,87 mm
Repeat accuracy	± 0,	15 mm	± 0,25 mm
Max speed	0,8 m/s	3 m/s	2,4 m/s
Pull-out force required	$\geq$ 3 N	$\geq$ 8 N	$\geq$ 15,5 N
Housing material	aluminu	aluminium die casting	
Rope material	S	steel rope, synthetically coated	
Enclosure rating			
Operating temperature	-40° +80°C (-40° +176°F)	-20° +80°C (-4° +176°F)	-40° +80°C (-40° +176°F)
Weight	350 g (12,35 oz) + encoder	700 g (24,69 oz) + encoder	2500 g (88,18 oz) + encoder
(EL-ER 58B) L*	95 mm	140 mm	114 mm
(EAM 58BR) L*	109 mm	154 mm	128 mm
(EAM 58B PROFIBUS) L*	135 mm	180 mm	154 mm
(EL-ER 58B) C*	58 mm	70 mm	99,5 mm
(EAM 58BR) C*	70 mm	82 mm	100,5 mm
(EAM 58B PROFIBUS) C*	98 mm	110 mm	127,2 mm

## Installation notes

A 5 mm wire extension is recommended before the measurement starting point.

This prevents the wire snapping back to the stop on rewinding. Wire should be pulled out straight in line with wire outlet.









EPLA is an absolute linear potentiometer assuring great reliability even in tough applications with heavy

The groove on the enclosure of the transducer represents an excellent alternative to the usual system of

Installation is also made simpler by the absence of variations on the electrical output signal outside of

EPLA is the right solution in machinery for material processing such as injection presses for plastic,

MAIN FEATURES

vibrations and shocks.

fastening with brackets.

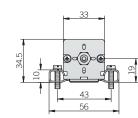
rubber and so on.

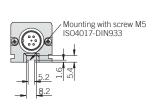
**ORDERING CODE** 

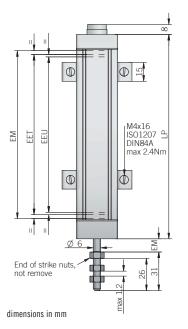
the theoretical electrical stroke.

## **EPLA** LINEAR POTENTIOMETER









CONNECTIONS				
Function	Cable	3 pin C3	4 pin C4	5 pin C5
+	blue	3	3	3
-	brown	1	1	1
OUTPUT	yellow	2	2	2
NC	/	/	/	/
NC	/	/	/	/
<u>+</u>	shield	/	<u>+</u>	/
C3 connector (3 pin) C4 connector (4 pin) C5 connector (5 pin)				

DIN 45322 solder side view FV





Ð

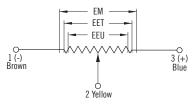




solder side view FV

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fixing kit (brackets, screws) included female connector not included, please refer to Accessories



CE RoHS



E EPLA	200	Х	10	<b>C</b> 5	A
SERIES linear potentiometer model EPLA mm from 5 see table for stroke a E	<b>STROKE</b> 50 to 900	IP 60 X IP 65 S TRAVI	EL <b>SPEED</b> 0 m/s 10		
		cable (s N 43650-A	OUTI tandard len 3 pin con 4 pin con 5 pin con	pUT TYPE gth 1 m) P nector C3	<b>RECTION</b> axial A

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ELECTRICAL SPECIFICATIONS		
Resolution	virtually infinite	
Independent linearity	± 0,05 %	
Repeatability	0,01 mm	
Resistance tolerance	± 20 %	
Recommended cursor current	< 0,1 µA	
Resistence thermal coefficient	-200 200 ppm / °C typical	
Output voltage temperature coefficient	$\leq$ 5 ppm / °C	
Power dissipation	3 W at 40 °C / 0 W at 120 °C	
Max cursor current	10 mA	
Applicable voltage	60 V DC max	
Electrical insulation	$> 100 \text{ M}\Omega$ , 500 V DC, 1 bar, 2 s	
Dielectric strenght	< 100 µA, 500 V AC, 50 Hz, 1 bar, 2 s	
RoHS	according to 2015/863/EU directive	

Important: data are valid if the transducer is used as a ratiometric device with a maximum applicable current  $\leq$  0,1  $\mu$ A

## MECHANICAL SPECIFICATIONS

MEGNANIGAL SPECIFICA	1110113
Stroke	50 - 100 - 150 - 200 - 300 - 350 - 400 - 450 - 500 - 600 - 750 - 900 mm
Useful electric stroke (EEU) (+ 3 / - 0 mm)	see model (mm)
Theoretical electric stroke (EET) (±1 mm)	EEU + 3 mm (50 150),EEU + 4 mm (200 300), 355 mm (350), 406 mm (400), 457 mm (450), 508 mm (500), 609 mm (600), 762 mm (750), 914 mm (900)
Mechanical stroke (EM)	EEU + 9 mm (50 150),EEU + 10 mm (200 300), 361 mm (350), 412 mm (400), 463 mm (450), 518 mm (500), 619 mm (600), 772 mm (750), 924 mm (900)
Resistance (on the EET)	5 kΩ (50 600) 10 kΩ (750 900)
Case length (LP)	EEU + 63 mm (50 150), EEU + 64 mm (200 300), 415 mm (350), 466 mm (400), 517 mm (450), 572 mm (500), 673 mm (600), 826 mm (750), 978 mm (900)
Travel speed	10 m/s max
Acceleration	200 m/s <sup>2</sup> max
Enclosure rating	X = IP 60 (IEC 60529) S = IP 65 (IEC 60529)
Shock	50 G, 11 ms (IEC 60068-2-27)
Vibration	20 G, 5 2000 Hz (IEC 60068-2-6)
Displacement force	3,5 N typical (IP 60) / 15 N typical (IP 65)
Housing material	anodized aluminium / Nylon 66 G
Pull shaft material	1.4305 / AISI 303 stainless steel
Mounting	brackets with variable center-to-center distance or M5 ISO4017 - DIN933 screw
Life	$>25 \ x \ 10^6 \ m$ strokes or $>100 \ x \ 10^6 \ m$ anoeuvres
Operating temperature <sup>1, 2</sup>	-30° +100°C (-22° +212°F)
Storage temperature <sup>2</sup>	-50° +120°C (-58° +248°F)

<sup>1</sup> measured on transducer

<sup>2</sup> condensation not allowed

Installation warning instructions:

connect the transducer according to the reported connections

DO NOT use it as a variable resistance

the transducer calibration has to be done setting the stroke in order to have an output signal between 1 % and 99 % of the voltage level







## **EPLB CYLINDRICAL LINEAR POTENTIOMETER**

RoHS

CE

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EPLB

## MAIN FEATURES

EPLB is an absolute linear potentiometer transducer.

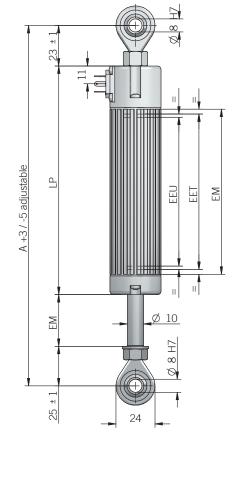
Mechanical mounting is made simpler by the presence of two spherical joints on the two sides and by the enclosure's cylindrical shape.

The main characteristic is the absence of variations on the electrical output signal outside of the theoretical electrical stroke.

Thanks to its robustness and precision EPLB represents a great solution in most mechanical application for automation.



ORDERING CODE	EPLB	300	S	5	Р	R
	SERIES cylindrical linear potentiometer model EPLB mm from see table for stroke a E	availability ENCLOSUR	E RATING IP 65 S TRAVI ma cable (st	EL SPEED x 5 m/s 5 OUTF tandard len 3 pin coni	p <b>UT TYPE</b> gth 1 m) P nector C3	
		DII M16	N 43650-C DIN 43322	4 pin coni 5 pin coni	nector C4 nector C5	
				-	OUTPUT DI	RECTION radial R

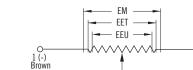


					MECHANICAL SPECIFIC	ATIONS
		Ø 10			Stroke	50 - 100 - 150 - 200 - 300 - 400 - 450 - 500 - 600 - 750 mm
					Useful electric stroke (EEU) (+3/-0 mm)	see model (mm)
		10 10 10 10 10 10 10 10 10 10 10 10 10 1			Theoretical electric stroke (EET) (±1 mm)	EEU + 3 mm (50 150), EEU + 4 mm (200 300), 406 mm (400), 457 mm (450), 508 mm (500), 609 mm (600), 762 mm (750)
25 ± 1	24				Mechanical stroke (EM)	EEU + 9 mm (50 150), EEU + 10 mm (200 300), 412 mm (400), 463 mm (450), 518 mm (500), 619 mm (600), 772 mm (750)
				25 (max	Resistance (on the EET)	
dimensions in mm					Case length (LP)	EEU + 130,5 mm (50 150), EEU + 131,5 mm (200 300), 539,5 mm (400), 590,5 mm (450), 665,5 mm (500), 766,5 mm (600), 919,5 mm (750)
CONNECTION Function	Cable	3 pin	4 pin	5 pin	Minimum interaxis length (A)	
		C3	C4	<u>C5</u>	Travel speed	5 m/s max
+	blue	3	3	3	Enclosure rating	IP 65 (IEC 60529)
-	brown	1	1	1	Shock	50 G, 11 ms (IEC 60068-2-27)
OUTPUT	yellow	2	2	2	Vibration	20 G, 5 2000 Hz (IEC 60068-2-6)
NC	1	/	1	/	Displacement force	$\leq 15 \text{ N}$
NC	/	/	/	/	Moving angle	± 25° max
<u>+</u>	shield	/	<u>+</u>	/	Housing material	anodized aluminium / Nylon 66 G
C3 connector (		onnector (4 pin) XIN 43650-C	C5 connector DIN 433	r (5 pin) 22	Rod material	1.4305 / AISI 303 stainless steel
solder side vie		er side view FV	solder side \		Mounting	2 selfloading and selfaligning ball-joints
		3			Life	$> 25 \times 10^6$ m strokes or $> 100 \times 10^6$ manoeuvres
	))	1000		2)))	Operating temperature <sup>1, 2</sup>	-30° +100°C (-22° +212°F)
					Storage temperature <sup>2</sup>	-50° +120°C (-58° +248°F)
female connector no	nt included, please r	efer to Accessories			<sup>1</sup> measured on transducer <sup>2</sup> condensation not allowed	
0	111		-0		Installation warning instructions: · connect the transducer according to t · DO NOT use it as a variable resistance	

<u>12</u> 9

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ELECTRICAL SPECIFICATIONS			
Resolution	virtually infinite		
Independent linearity	± 0,05 %		
Repeatability	0,01 mm		
<b>Resistance tolerance</b>	± 20 %		
Recommended cursor current	< 0,1 µA		
Output voltage temperature coefficient	$\leq$ 1,5 ppm / °C		
Power dissipation	3 W at 40 °C / 0 W at 120 °C		
Max cursor current	10 mA		
Applicable voltage	60 V max		
Electrical insulation	$>100~\text{M}\Omega\text{,}~500~\text{V}$ DC, 1 bar, 2 s		
Dielectric strenght	$<$ 100 $\mu\text{A},$ 500 V AC, 50 Hz, 1 bar, 2 s		
RoHS	according to 2015/863/EU directive		

Important: data are valid if the transducer is used as a ratiometric device with a maximum applicable current  $\leq$  0,1  $\mu$ A

the transducer calibration has to be done setting the stroke in order to have an output signal between 1 % and 99 % of the voltage level







## **EPLC RODLESS LINEAR POTENTIOMETER**

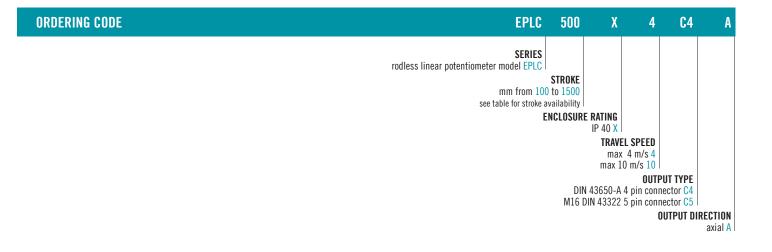
CE

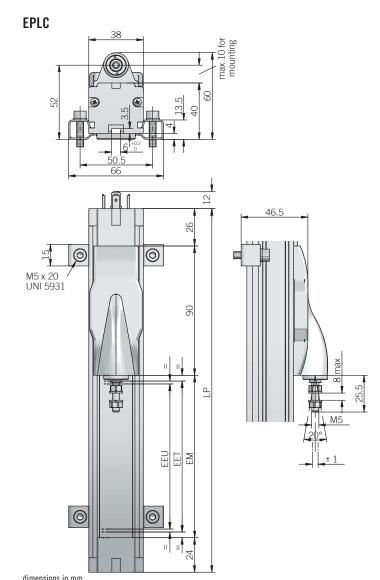


Eltra 195

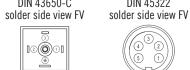
EPLC is an absolute linear potentiometer transducer without internal rod. This transducer is characterized by a cursor with integrated coupling sliding on the axis. The main characteristic is the absence of variations on the electrical output signal outside of the theoretical electrical stroke.







Function	4 pin C4	5 pin C5
+	3	3
-	1	1
OUTPUT	2	2
NC	/	/
NC	/	/
÷	÷	/



fixing kit (brackets, screws, grower) included

female connector not included, please refer to Accessories



ELECTRICAL SPECIFICA	TIONS
Resolution	virtually infinite
Independent linearity	± 0,05 %
Repeatability	0,01 mm
Resistance tolerance	± 20 %
Recommended cursor current	< 0,1 µA
Resistance temperature coefficient	-200 200 ppm / °C typical
Output voltage temperature coefficient	$\leq$ 5 ppm / °C typical
Power dissipation	3 W at 40 °C / 0 W at 120 °C
Max cursor current	10 mA max
Applicable voltage	60 V max
Electrical insulation	$>$ 100 M $\Omega,$ 500 V DC, 1 bar, 2 s
Dielectric strenght	$<$ 100 $\mu\text{A},$ 500 V AC, 50 Hz, 1bar, 2 s
RoHS	according to 2015/863/EU directive
Important: data are valid if the transducer $\leq 0.1 \text{ uA}$	r is used as a ratiometric device with a maximum applicable current
MECHANICAL SPECIFICA	ATIONS
Stroke	100 - 150 - 200 - 300 - 400 - 500 - 600 - 700 - 850 - 900 - 1000 - 1250 - 1500 mm
Useful electric stroke (EEU) (+3/-0 mm)	see model (mm)
Theoretical electric stroke (EET) (±1 mm)	103 mm (100), 153 mm (150), 204 mm (200), 305 mm (300), 406 mm (400), 509 mm (500), 611 mm (600), 713 mm (700), 865 mm (850), 915 mm (900), 1017 mm (1000),1271 mm (1250), 1521 mm (1500)
Mechanical stroke (EM)	EET + 10mm (100 1500)
Resistance (on the EET)	5 kΩ (100 300) 10 kΩ (400 1000) 20 kΩ (1250 1500)
Case length (LP)	EET + 150mm (100 1500)
Travel speed	4 = 4 m/s max 10 = 10 m/s max
Acceleration	200 m/s <sup>2</sup> max
Enclosure rating	IP 40 (IEC 60529)
Shock	50 G, 11 ms (IEC 60068-2-27)
Vibration	20 G, 5 2000 Hz (IEC 60068-2-6)
Displacement force	$\leq$ 1,2 N max
Housing material	anodized aluminium / Nylon 66 G 25
Mounting	brackets with variable center-to-center distance with M6 screw ISO4017 - DIN933
Operating temperature <sup>1, 2</sup>	-30° +100°C (-22° +212°F)
Storage temperature <sup>2</sup>	-50° +120°C (-58° +248°F)
<sup>1</sup> measured on transducer	

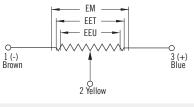
<sup>2</sup> condensation not allowed

Installation warning instructions:

· connect the transducer according to the reported connections

DO NOT use it as a variable resistance

the transducer calibration has to be done setting the stroke in order to have an output signal between  $1\,$ % and 99 % of the voltage level









## **EPLT** LINEAR POTENTIOMETER WITH BALL TIP

CE

EPLT



Eltra 195-2020

EPLT is an absolute linear potentiometer transducer.

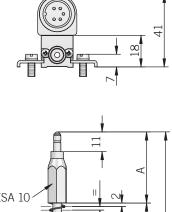
This model is characterized by the absence of cursor and the presence of a sensing system, composed by a moving rod, stainless steel sphere mounted on a threaded tip with a spring.

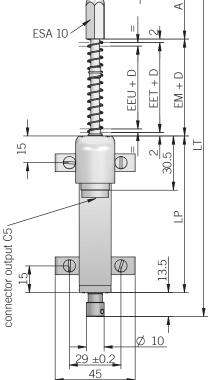
This transducer is suitable for applications where short strokes are requested.

The presence of the spring assures an automatic head positioning making this device suitable for being used in precise applications on cams or to control products coming from automatic production line. EPLT is also characterized by the absence of variations on the electrical output signal outside of the theoretical electrical stroke.









dimensions in mm

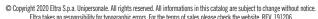
## CONNECTIONS

Function	Cable P	5 pin C5
+	blue	3
-	brown	1
OUTPUT	yellow	2
NC	/	/
NC	/	/
Ŧ	shield	/

C5 connector (5 pin) DIN 45322 solder side view FV



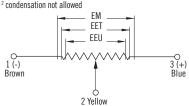
fixing kit (brackets, M4x10 screws, washer) and tip with ball included female connector not included, please refer to Accessories



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ELECTRICAL SPECIFICA	TIO <u>ns</u>					
Resolution	virtua	lly infinite	Э			
Stroke	mm	10	25	50	75	100
Independent linearity	%	± 0,3	± 0,2	± 0,1	± 0,1	± 0,1
Resistance tolerance	± 20 °	%	1			· · · · ·
Recommended cursor current	< 0,1	μA				
Output voltage temperature coefficient	< 1,5	ppm / °C				
Power dissipation at 40 °C (0 W at +120 °C)	W	0,2	0,6	1,2	1,8	2,4
Max cursor current	10 mA	max				
Max applicable voltage	V	14	25	60	60	60
Electrical insulation	> 100	MΩ, 50	) V DC, 1	bar, 2 s		
Dielectric strenght	< 100	µA, 500	V AC, 50	Hz, 1bar,	2 s	
RoHS		-		EU directi		
Important: data are valid if the transducer $\leq 0.1 \text{ uA}$	r is used a	is a ratiome	tric device w	vith a maxim	um applical	ble current
MECHANICAL SPECIFICA	ATION	S				
Stroke	mm	10	25	50	75	100
Useful electric stroke (EEU) (+1/-0 mm)	mm	10	25	50	76	101
Theoretical electric stroke (EET) (±1 mm)	mm	11	26	51	76	101
Mechanical stroke (EM)	mm	15	30	55	81	106
Resistance (on EET)	kΩ	1	1	5	5	5
Case length (LP)	mm	48	63	88	114	139
Sensing probe length	mm	32	32	40	40	40
Additional length (D)	mm	-	-	-	5	11
Total length (LT)	mm	108	138	196	251	307
Travel speed	10 m/	s max				
Enclosure rating	IP 40	(IEC 6052	29)			
Shock	50 G,	11 ms (IE	C 60068	-2-27)		
Vibration	20 G,	5 2000	) Hz (IEC	60068-2-	-6)	
Displacement force	$\leq$ 4 N					
Housing material				ylon 66 G	25	
Rod material		5 / AISI 3				
Mounting				enter-to-		
Life				> 100 x 1	-	tions
Operating temperature <sup>1, 2</sup>				. +212°F		
Storage temperature <sup>2</sup>	-50°.	+120°(	C (-58°	. +248°F	)	
<sup>1</sup> measured on transducer <sup>2</sup> condensation not allowed						



Installation warning instructions:

- connect the transducer according to the reported connections

DO NOT use it as a variable resistance

the transducer calibration has to be done setting the stroke in order to have an output signal between 1% and 99 % of the voltage level







## **EMSPA** LINEAR MAGNETOSTRICTIVE TRANSDUCER WITH ANALOGUE OUTPUT

## MAIN CHARACTERISTICS

EMSPA is an absolute linear magnetostrictive transducer with analog interface. Thanks to the absence of electrical contact on the enclosure there is no issue of wear and deterioration during working life.

Magnetostrictive technology guaranties great performances of speed and accuracy.

High reliability and simple installation even for applications with mechanical stresses, shocks or high contamination are assured by the compact size and the rugged enclosure.



CE

ORDERING CODE	EMSPA	500	S	20D	10	Р	A
	SERIES						
	linear magnetostrictive transducer with analogue output EMSPA						
		STROKE					
	mm from 5						
	see table for stroke						
		ENGLUSU	IP 67 S				
				T SIGNAL			
			ursor (stand				
	0 10 V DC 0 10 V DC / 2 curs	/ 1 CUrson	r position/s stroko 400	peed 10P			
	0 10 V DC / 2 Cuis	42	20 mA / 1 c	ursor 20S			
	4 20 mA						
	4 20 mA / 2 curs	ors (min.	stroke 400	mm) <mark>20D</mark>			
					EL SPEED		
				max	10 m/s 10		
				aabla (-		UT TYPE	
					tandard leng 2 5 pin conn		
					2 8 pin conn		
			M16	DIN 45322	6 pin conn	ector C6	
			M16	DIN 45326	8 pin conn		
					0	UTPUT DIRI	
							axial A

Mounting with M5 x10 screw EE = model 96 10 Tightening torque < 1.1 Nm / LT EE = model 96 **⊕** 

allowed lateral deviation ± 2 mm

dimensions in mm

EMSPA

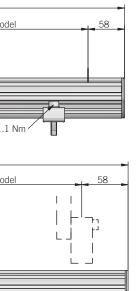
· brackets, cursors and female connector not included, please refer to Accessories

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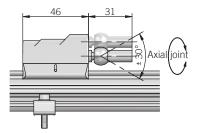
32

<b>ELECTRICAL SPECIFICA</b>	TIONS		MECHANICAL SPECIFICA	ATIONS
Resolution Output signal	0 10 V DC	4 20 mA	Stroke	50 - 100 - 150 - 200 - 250 - 300 - 350 - 400 - 450 - 500 - 600 - 700 - 800 - 900 - 1000 - 1100 - 1200 - 1300 - 1400 - 1500 mm
Output alarm value	,	21 mA	Electric stroke (EE)	see model (mm)
Output max value		30 mA	Overall dimension (LT)	EE + 154 mm
Power supply <sup>1</sup>	19,2 28,8 V DC		Enclosure rating	IP 67 (IEC 60529)
Power ripple		00.1	Detected measurement	displacement / speed
Current consumption		90 mA max	Travel speed	10 m/s max
Output load		< 500 Ω	Acceleration	100 m/s² max
Output ripple	$\leq \pm 0.01$ % FS (min ± 0	),060 mm)	Speed measurament range	min 0 0,1 m/s max 0 10 m/s
	typical with sliding cursor $\leq \pm 0.02$ % FS with floa	ting cursor	Speed accuracy	< 2 %
Indipendent linearity	(working distance 2 5 mm)	0	Shock	100 G, 11 ms, single shock (IEC 60068-2-27)
	$\leq \pm 0.04$ % FS with floa (working distance 5 7 mm)	iting cursor	Vibration	12 G, 10 2000 Hz (IEC 680068-2-6)
Repeatability	< 0.01 mm		Housing material	anodized aluminium / Nylon 66 G 25
Hysteresis	- / -		Cursor type	sliding or floating cursor
	0,5 ms (50 300)		Temperature coefficient	0,005 % FS / °C
Sampling time	1 ms (350 1100)		Operating temperature <sup>2, 3</sup>	-30° +75°C (-22° +167°F)
	1,5 ms (1200 1500)		Storage temperature <sup>3</sup>	-40° +100°C (-40° +212°F)
Protection against overvoltage			<sup>1</sup> as measured at the transducer without <sup>3</sup> measured on transducer	cable influences
Protection against polarity inversion			<sup>4</sup> condensation not allowed	
Protection against power supply on output				
Electrical insulation	500 V DC			
Electromagnetic compatibility	according to 2014/30/E	U directive		
RoHS	according to 2015/863/	EU directive		





LT





## LINEAR TRANSDUCERS | EMSPA



## MAIN CHARACTERISTICS

EMSPB is an absolute linear magnetostrictive transducer with analogue interface. Thanks to the absence of electrical contact on the enclosure there is no issue of wear and deterioration during working life.

Magnetostrictive technology guaranties great performances of speed and precision. High reliability and simple installation even for applications with mechanical stresses, shocks or high contamination are assured by the compact size and the rugged enclosure.

**ORDERING CODE** 

CONNECTIONS 5 pin M12 8 pin M12 6 pin M16 8 pin M16 Function Cable S5 **S8** C6 Ρ **C**8 + V DC brown 5 7 5 7 0 V white Δ 6 8 6 **Output cursor 1** 0 ... 10 V 4 ... 20 mA 5 5 (1\*) 1 1 grey OV cursor 1 pink 2 1 2 2 Inverse output cursor 1 Output cursor 2 3 3 3 3 Output speed yellow 10 ... Ó V 20 ... 4 mA 0 V **Output cursor 1** 2 2 Δ 6 pink **Output cursor 2** Output speed

S5 connector (5 pin) M12 A coded solder side view FV

2 1

(3) (4)

M12 A coded solder side view FV 3 8 (

S8 connector (8 pin)



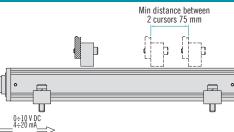
C6 connector (6 pin)

C8 connector (8 pin) DIN 45326 solder side view FV

The transducer enclosure has to be connected to ground only on the control system side by the cable shield.

To guarantee the correct electrical insulation of the transducer from the machine, always assemble the brackets using the plastic washers included.

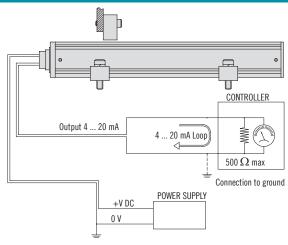
## **INSTALLATION EXAMPLE**



For multi-cursor model, the cursors have to work in the same conditions of distance and temperature. Cursors must be installed on a support made of non-magnetic material (like brass, aluminium or AISI316 stainless steel).

The installation kit provides two screws, two nuts and two washers (all made of brass). The cursor must be installed with maximum attention to horizontal alignment with the transducer axis (maximum tolerance is  $\pm 2$  mm), distance from the transducer surface has to be within the range from 2 to 7 mm.

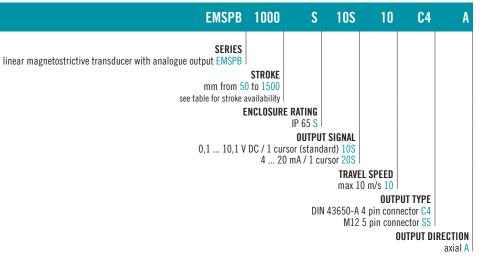
## **APPLICATION EXAMPLE (CURRENT OUTPUT)**



Eltra

## EMSPB LINEAR MAGNETOSTRICTIVE TRANSDUCER WITH ANALOGUE OUTPU

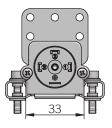


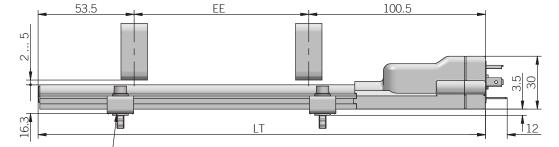






## EMSPB





**ELECTRICAL SPECIFICATIONS** 

dimensions in mm

Closing force < 0,24 Nm

· brackets, cursors and female connector not included, please refer to Accessories

## MECHANICAL SPECIFICATIONS

Stroke	50 - 100 - 150 - 200 - 225 - 300 - 350 - 400 - 450 - 500 - 600 - 700 - 800 - 900 - 1000 - 1100 - 1200 - 1300 - 1400 - 1500 mm
Electric stroke (EE)	see model (mm)
Overall dimension (LT)	EE + 154 mm
Enclosure rating	IP 65 (IEC 60529)
Detected measurement	displacement
Travel speed	10 m/s max
Acceleration	100 m/s <sup>2</sup> max
Shock	100 G, 11 ms, single shot (IEC 68000-2-27)
Vibration	12 G, 10 2000 Hz (IEC 68000-2-6)
Housing material	anodized aluminium / Nylon 66 G 25
Cursor type	floating cursor
Temperature coefficient	$\leq$ 0,01 % FS / °C (min. 0,015 mm / ° C)
Operating temperature <sup>2, 3</sup>	-20° +75°C (-4° +167°F)
Storage temperature <sup>3</sup>	-40° +100°C (-40° +212°F)

## CONNECTIONS

Function	4 pin C4	M12 5 pin \$5
+V DC	3	5
0 V	1	4
OUTPUT	2	1
0 V output	/	2
÷	shield	/

C4 connector (4 pin) DIN 43650-A solder side view FV

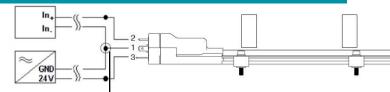
# M12 connector (5 pin)



M12 A coded solder side view FV



## APPLICATION EXAMPLE (CURRENT OUTPUT)



Note: connect as close as possible to transducer

Resolution	virtually infinite		
Output signal	0,1 10,1 V DC	4 20 mA	
Output alarm value	10,5 V DC	21 mA	
Output value max	12 V DC	30 mA	
Power supply <sup>1</sup>	19,2 28,8 V DC		
Power ripple	1 Vpp max		
Current consumption	35 mA max	60 mA max	
Output load	$\geq$ 10 k $\Omega$	50 500 Ω	
Indipendent linearity	± 0,04 % FS max (min ± 0,09 mm)		
Repeatability	$\leq$ 0,01 mm		
Hysteresis	≤ 0,02 mm		
Sampling time	1 ms (50 600) 1,5 ms (650 900) 2 ms (1000 1300) 3 ms (1400 1500)		
Protection against overvoltage	yes		
Protection against polarity inversion	yes		
Protection against power supply on output	yes		
Electrical insulation	50 V DC		
Electromagnetic			

Electromagnetic according to 2014/30/EU directive compatibility **RoHS** according to 2015/863/EU directive <sup>1</sup> as measured at the transducer without cable influences

<sup>3</sup> measured on transducer <sup>4</sup> condensation not allowed

## **INSTALLATION NOTES**

For multi-cursor model, the cursors have to work in the same conditions of distance and temperature. Cursors must be installed on a support made of non-magnetic material (like brass, aluminium or AISI316 stainless steel). The installation kit provides two screws, two nuts and two washers (all made of

brass). The cursor must be installed with maximum attention to horizontal alignment with the transducer axis (maximum tolerance is  $\pm 2$  mm), distance from the transducer surface has to be within the range from 2 to 5 mm.

## MAIN CHARACTERISTICS

EMSPS is an absolute linear magnetostrictive transducer featuring a digital RS-422 SSI compliant output.

The main characteristic of magnetostrictive transducers is the absence of electric contact on the enclosure there is no issue of wear and deterioration during working life guaranteeing high displacement speed and precision.

High reliability and simple installation even for applications with mechanical stresses, shocks or high contamination are assured by the compact size and the rugged enclosure.

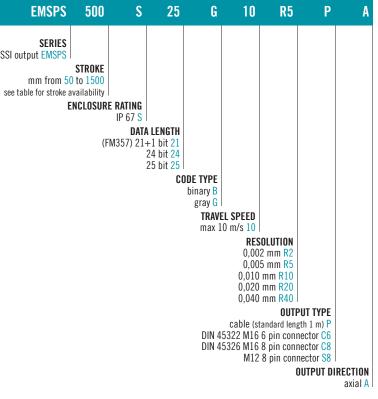
## **ORDERING CODE**

linear magnetostrictive transducer with SSI output EMSPS



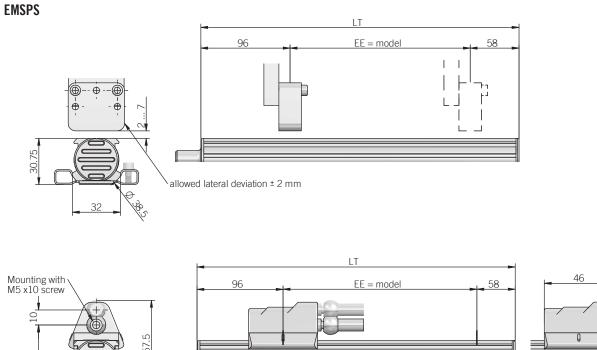
## **EMSPS** LINEAR MAGNETOSTRICTIVE TRANSDUCER WITH SSI OUTPUT



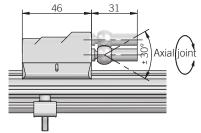




## LINEAR TRANSDUCERS | EMSPS



Tightening torque < 1.1



dimensions in mm

· brackets, cursors and female connector not included, please refer to Accessories

ELECTRICAL SPECIFICA	TIONS
Resolution	2 - 5 - 10 - 20 - 40 µm
Indipendent linearity	$\leq \pm 0.01$ % FS (min $\pm 0.060$ mm) typical with sliding cursor $\leq \pm 0.02$ % FS typical with floating cursor
Repeatability	< 0,01 mm
Hysteresis	$\leq \pm$ 0,005 % FS (min 0,010 mm)
Power supply <sup>1</sup>	10 32 V DC
Power ripple	1 Vpp max
Max load current	50 mA max
Electrical interface	RS-422
SSI output code	binary or gray
Clock frequency	50 kHz 1 MHz
SSI monostable time (Tm)	16 µs
SSI frame	21 / 24 / 25 bit data length
<b>Counting direction</b>	increase
Protection against overvoltage	yes
Protection against polarity inversion	yes
Self-resetting internal fuse	yes
<b>Electrical insulation</b>	500 V DC (+V DC / earth)
Electromagnetic compatibility	according to 2014/30/EU directive
RoHS	according to 2015/863/EU directive

MECHANICAL SPECIFIC/ Stroke	50 - 100 - 150 - 200 - 250 - 300 - 350 - 400 - 450 - 500 - 600 - 700 - 800 - 900 - 1000 - 1100 - 1200 - 1300 - 1400 - 1500 mm
Electric stroke (EE)	see model (mm)
Overall dimensions (LT)	EE + 154 mm
Enclosure rating	IP 67 (IEC 60529)
Detected measurement	displacement
Scale orientation	increasing
Travel speed	10 m/s max
Acceleration	100 m/s² max
Shock	100 G, 11 ms, single shot (IEC 68000-2-27)
Vibration	12 G, 10 2000 Hz (IEC 68000-2-6)
Housing material	anodized aluminium / Nylon 66 G 25
Cursor type	sliding or floating cursor
Temperature coefficient	20 ppm FS / °C
Operating temperature <sup>2, 3</sup>	-30° +90°C (-22° +194°F)
Storage temperature <sup>3</sup>	-40° +100°C (-40° +212°F)
s measured at the transducer without neasured on transducer ondensation not allowed	cable influences

INNECTIONS				
Function	Cable P	8 pin M12 S8	6 pin M16 C6	8 pin M16 C8
+ V DC	blue / white	7	5	7
0 V	blue	6	6	6
DATA +	orange / white	2	2	2
DATA -	orange	5	1	5
CLOCK +	green / white	3	3	1
CLOCK -	green	1	4	3

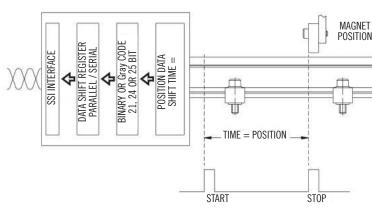
S8 connector (8 pin) M12 A coded solder side view FV

C8 connector (8 pin) DIN 45326 C6 connector (6 pin) DIN 45322 solder side view FV

solder side view FV

The transducer enclosure and cable shield have to be connected to ground on both sides.

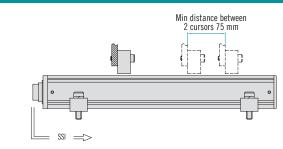
## SSI BLOCK DIAGRAM



SSI output goes to 0 if the echo is absent (magnet out of measurement range or internal device error)

SSI CABLE LENGTH					
Cable length	< 3 m	< 50 m	< 100 m	< 200 m	< 400 m
Baud rate	1 Mbaud	400 kbaud	300 kbaud	200 kbaud	100 kbaud

## INSTALLATION EXAMPLE



For multi-cursor model, the cursors have to work in the same conditions of distance and temperature. Cursors must be installed on a support made of non-magnetic material (like brass, aluminium or AISI316 stainless steel). The installation kit provides two screws, two nuts and two washers (all made of brass). The cursor must be installed with maximum attention to horizontal alignment with the transducer axis (maximum tolerance is  $\pm 2$  mm), distance from the transducer surface has to be within the range from 2 to 7 mm.



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## LINEAR TRANSDUCERS | EMSPS







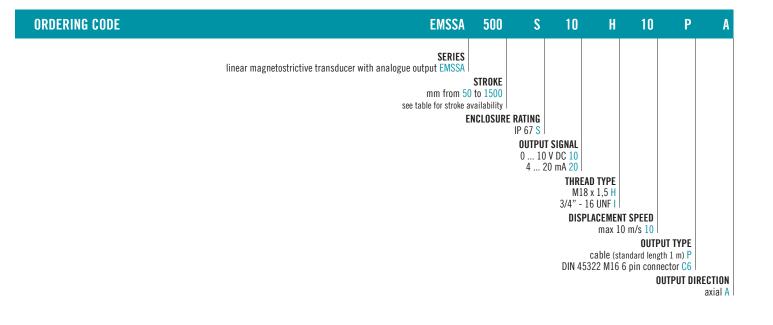


## **EMSSA** LINEAR MAGNETOSTRICTIVE ROD TRANSDUCER WITH ANALOGUE OUTPUT

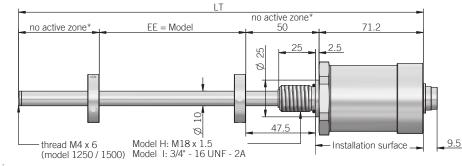
## MAIN CHARACTERISTICS

EMSSA is an absolute linear magnetostrictive transducer featuring an analogue interface. Main characteristics of magnetostrictive transducers is the absence of electric contact on the enclosure there is no issue of wear and deterioration during working life guaranteeing high displacement speed and precision.

High reliability and simple installation even for applications with mechanical stresses, shocks or high contamination are assured by the compact size and the rugged enclosure. This series has been designed for being mounted internally to high applications (350 bar, 500 bar peak) such as hydraulic or pneumatic cylinders.



EMSSA no active zone\*



dimensions in mm

CE

OR 15,4 x 2,1 (mod.H) / OR 16,36 x 2,21 (mod.I) included

Cursors and female connector not included, please refer to Accessories

ELECTRICAL SPECIFICATIONS		MECHANICAL SPECIFICA	MECHANICAL SPECIFICATIONS			
Resolution	First Contraction of the second se		Stroke	50 - 100 - 150 - 200 - 250 - 300 - 350 - 400 - 450 - 500 - 600 - 700 - 800 - 900 - 1000 - 1250 - 1500 mm		
Output signal	0 10 V DC	4 20 mA	Electric stroke (EE)	see model (mm)		
Output alarm value	10,5 V DC	21 mA				
Output value max		30 mA	Overall dimensions (LT)	EE + 176,2 mm (mod. 50 900) EE + 181,2 mm (mod. 1000 1500)		
Power supply <sup>1</sup>	19,2 28,8 V DC		Enclosure rating	IP 67 (IEC 60529)		
Power ripple	1 Vpp max		Detected measurement	displacement		
Current consumption	70 mA max	90 mA max	Travel speed	10 m/s max		
Output load		< 500 Ω	Acceleration	100 m/s² max		
Output ripple	pple < 5 mVpp			min 0 0.1 m/s		
Indipendent linearity	$\leq$ $\pm$ 0,02 % FS (min	± 0,060 mm)	Speed measurament range	max 0 10 m/s		
Repeatability	< 0,01 mm		Speed accuracy	< 2 %		
Hysteresis	< 0,01 mm		Shock	100 G, 11 ms, single shock (IEC 60068-2-27)		
Sampling time 1 m	0,5 ms (mod. 50 200) 1 ms (mod. 400 1000) 1.5 ms (mod. 1250 1500)		Vibration	12 G, 10 2000 Hz (IEC 680068-2-6)		
			Rod / housing material	1.4401 / AISI 316 stainless steel		
Protection against			Operative pressure	350 bar (500 bar peak)		
overvoltage	yes		Cursor type	floating cursor		
Protection against			Temperature coefficient	$\leq$ 0,01 % FS / °C		
polarity inversion	300		Operating temperature <sup>2, 3</sup>	-30° +75°C (-22° +167°F)		
Protection against power supply on output			Storage temperature <sup>3</sup>			
Electrical insulation	500 V DC		<sup>1</sup> as measured at the transducer without <sup>3</sup> measured on transducer	<sup>1</sup> as measured at the transducer without cable influences <sup>3</sup> measured on transducer		
Electromagnetic compatibility	according to 2014/3	80/EU directive	<sup>4</sup> condensation not allowed			
RoHS	according to 2015/8	863/EU directive				

CONNECTIONS			
Function	Cable P	6 pin M16 C6	
+ V DC	brown	5	
0 V	white	6	
Output cursor 1 0 10 V 4 20 mA	grey	1	
0 V cursor 1	pink	2	
Inverse output cursor 1 10 0 V 20 4 mA	yellow	3	
O V inverse output cursor 1	pink	4	

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Eltra 195-2020

\* = 55 mm up to stroke 1000 mm, from 1250 mm consider 60 mm due to M4 threaded hole

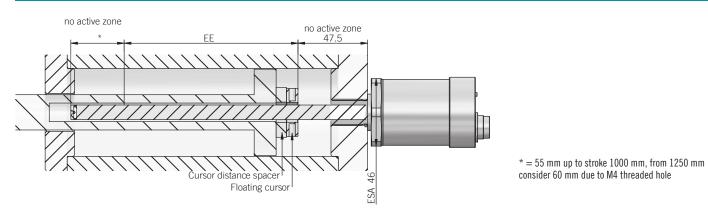








## **INSTALLATION EXAMPLE**



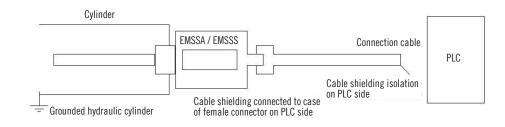
For correct installation of rod-type magnetostrictive transducers in hydraulic cylinders, remember that the cylinder head must be made of non-magnetic material where the threaded hole will be drilled to install the transducer. If not, the residual magnetisation caused by drilling the threaded hole must be less than 4 Gauss. Sealing surface must be free from scratches longitudinal or spiral

Ro 1.6 µm for sealing with non pulsating pressure Ro 0.8 µm for seals with pulsating pressure

Suggested o-ring (model H) Parker 6-349 15,4 x 2,1 Material: Viton 90° Shore A Mixes: Parker N552-90

Suggested o-ring (model I) Parker 3-908 16,36 x 2,21 Material: Viton 90° Shore A Mixes: Parker N552-90

## ELECTRICAL CONNECTION EXAMPLE



The transducer must be installed away from sources of magnetic fields, both static and 50 Hz (electric motors, solenoids, etc.).

with floating cursor assembly support must be made with nonmagnetic material

the transducer connection cable must be wired separate from power cables and/or solenoid controls, drives, or remote switches power supply must be drawn from dedicated power supply and connected directly to power terminals as near as possible

since the transducer cursor is a magnet, make sure there are no iron filings or small fragments of magnetic metal near the transducer. This could produce an

accumulation of material on the cursor, with consequent sliding problems

if the transducer is installed in a cylinder isolated from the ground, the cable shielding on PLC side must be grounded

with multiple cursors (two or more), cursors distance must be minimum 75 mm each

# 

## 255

## MAIN CHARACTERISTICS

EMSSS is an absolute linear magnetostrictive transducer featuring a SSI output. Main characteristics of magnetostrictive transducer is the absence of electric contact on the enclosure so there is no issue of wear and deterioration during working life guaranteeing high displacement speed and precision.

High reliability and simple installation even for applications with mechanical stresses, shocks or high contamination are assured by the compact size and the rugged enclosure. This series has been designed for being mounted internally to high preassure (350 bar, 500 bar peak) such as hydraulic or pneumatic cylinders.

## **ORDERING CODE**

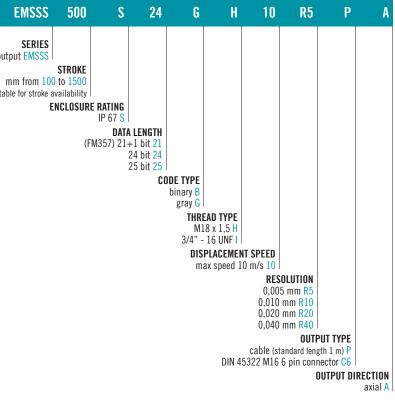
## SERIES

linear magnetostrictive transducer with SSI output EMSSS

see table for stroke availability

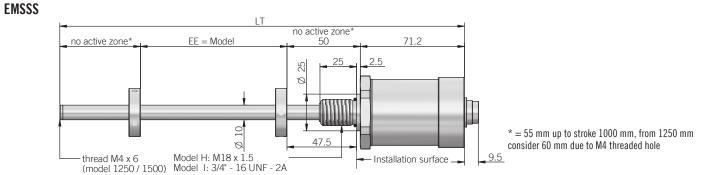
## EMSSS LINEAR MAGNETOSTRICTIVE ROD TRANSDUCER WITH SSI OUTPU







## LINEAR TRANSDUCERS | EMSSS



dimensions in mm

• OR 15,4 x 2,1 (mod.H) / OR 16,36 x 2,21 (mod.I) included

Cursors and female connector not included, please refer to Accessories

ELECTRICAL SPECIFICA	TIONS
Resolution	5 - 10 - 20 - 40 µm
Indipendent linearity	$\leq \pm 0.02$ % FS (min $\pm 0.060$ mm)
Repeatability	< 0,01 mm
Hysteresis	$\leq \pm 0,005$ % FS (min 0,010 mm)
Sampling time	1 ms (mod. 100 1000) 2 ms (mod. 1250 1500)
Power supply <sup>1</sup>	10 32 V DC
Power ripple	1 Vpp max
Max load current	50 mA max
Electrical interface	RS-422
SSI output code	binary or gray
Clock frequency	50 kHz 1 MHz
SSI monostable time (Tm)	16 µs
SSI frame	21 / 24 / 25 bit data length
Counting direction	increase
Protection against overvoltage	yes
Protection against polarity inversion	yes
Self-resetting internal fuse	yes
<b>Electrical insulation</b>	500 V DC (+V DC / earth)
Electromagnetic compatibility	according to 2014/30/EU directive
Electromagnetic	according to 2015/863/EU directive

## CONNECTIONS

Function	Cable P	6 pin M16 C6	
+ V DC	blue / white	5	
0 V	blue	6	
DATA +	brown / white	2	
DATA -	orange	1	
CLOCK +	green / white	3	
CLOCK -	green	4	

MECHANICAL SPECIFIC	ATIONS		
Stroke	100 - 150 - 200 - 300 - 400 - 450 - 500 - 600 - 700 - 800 - 900 - 1000 - 1250 - 1500 mm		
Electric stroke (EE)	see model (mm)		
Overall dimensions (LT)	EE + 176,2 mm (mod. 100 1000) EE + 181,2 mm (mod. 1250 1500)		
Enclosure rating	IP 67 (IEC 60529)		
Detected measurement	displacement		
Travel speed	10 m/s max		
Acceleration	100 m/s² max		
Speed measurament range	min 0 0,1 m/s max 0 10 m/s		
Speed accuracy	< 2 %		
Shock	100 G, 11 ms, single shock (IEC 60068-2-27)		
Vibration	12 G, 10 2000 Hz (IEC 680068-2-6)		
Rod / housing material	1.4401 / AISI 316 stainless steel		
Operative pressure	350 bar (500 bar peak)		
Cursor type	floating cursor		
Temperature coefficient	20 ppm FS / °C		
Operating temperature <sup>2, 3</sup>	-30° +90°C (-22° +194°F)		
Storage temperature <sup>3</sup>	-40° +100°C (-40° +212°F)		
as measured at the transducer without	cable influences		

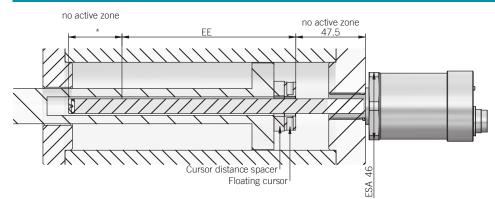
<sup>3</sup> measured on transducer

<sup>4</sup> condensation not allowed

C6 connector (6 pin) DIN 45322 solder side view FV



## **INSTALLATION EXAMPLE**



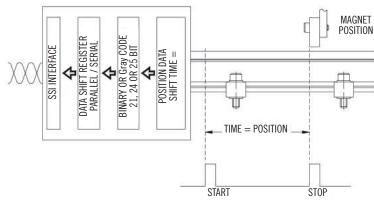
For the correct installation of rod-type magnetostrictive transducers in hydraulic cylinders, remember that the cylinder head must be made of non-magnetic material where the threaded hole will be drilled to install the transducer. If not, the residual magnetisation caused by drilling the threaded hole must be less than 4 Gauss. Sealing surface must be free from scratches longitudinal or spiral

Ro 1,6 µm for sealing with non pulsating pressure Ro 0,8 µm for seals with pulsating pressure

Suggested o-ring (model H) Parker 6-349 15,4 x 2,1 Material: Viton 90° Shore A Mixes: Parker N552-90

Suggested o-ring (model I) Parker 3-908 16,36 x 2,21 Material: Viton 90° Shore A Mixes: Parker N552-90

## SSI BLOCK DIAGRAM



SSI output goes to 0 if the echo is absent (magnet out of measurement range or internal device error)

SSI CABLE LENGTH					
Cable length	< 3 m	< 50 m	< 100 m	< 200 m	< 400 m
Baud rate	1 Mbaud	400 kbaud	300 kbaud	200 kbaud	100 kbaud

## INSTALLATION NOTES

The transducer must be installed away from sources of magnetic fields, both static and 50 Hz (electric motors, solenoids, etc.).

- with floating cursor assembly support must be made with nonmagnetic material
- the transducer connection cable must be wired separate from power cables and/or solenoid controls, drives, or remote switches
- power supply must be drawn from dedicated power supply and connected directly to power terminals as near as possible
- accumulation of material on the cursor, with consequent sliding problems cable shield must be connected on both sides (PLC and transducer)
- if the transducer is installed in a cylinder isolated from the ground, the cable shielding on PLC side must be grounded.



\* = 55 mm up to stroke 1000 mm, from 1250 mm consider 60 mm due to M4 threaded hole



since the transducer cursor is a magnet, make sure there are no iron filings or small fragments of magnetic metal near the transducer. This could produce an

